

The first assumption is that the handwritten strokes are already grouped into recognizable objects, which represent mathematical symbols or arrows. The information we keep from the objects are their identity obtained using a classifier [4], and their position and size encoded as bounding box.

The second assumption concerns the position of mathematical expressions and arrows: each expression is associated with at least one incoming or outgoing arrow. This assumption usually holds for the majority of commutative diagrams, because connections between expressions are the relationships that the diagrams express. We can ignore expressions without any apparent relationship to other ones without modifying the recognition of diagram.

The third assumption affects the layout of the mathematical expressions. We assume that the expressions are arranged in a tabular layout. This assumption simplifies the recognition as well as the LaTeX-code generation. This assumption does not hold for all commutative diagrams, but any diagram can be rewritten satisfying it.

Our algorithm for recognizing commutative diagrams consists of three main steps. The first step segments the handwritten strokes into arrows and non-arrows (mathematical symbols). The second step creates an initial grouping of the symbols, which are located inside the grid cells or outside forming arrow labels. The third step combines the initial grouping into mathematical expressions and reconstruct the tabular arrangement that best fits them. The following sections explain these steps in detail.

3. Arrow recognition

We recognize arrows using a method similar to Kara's and Stahovich's [2]. They suppose that arrows are formed with a continuous stroke or with two strokes. Both arrow shapes have five characteristic points that determine the arrow's shaft and head, see Fig. 2. If the arrow is formed with one stroke, then the points B , C and D are the last three stroke's corners, E is the stroke's last point, and A is a point in the stroke that lies at a short distance from B . If the arrow is formed with two strokes, B is the last point of the first stroke, C is the first point in the second stroke, and the other points are as before. Note that the analysis concentrate on an area that contains the arrow's head, so it allow us to recognize arrows with a great variety of shaft's shapes. Below we explain how one can decide whether one or two strokes form an arrow after locating these characteristic points.

In contrast to Kara and Stahovich, we use a classifier to recognize arrows. As preprocessing step, we first rotate all points so that the segment \overline{AB} is horizontal and A lies at the left of B . Then we exchange the points C and E , if C lies below the line \overline{AB} . Finally, we scale all points so

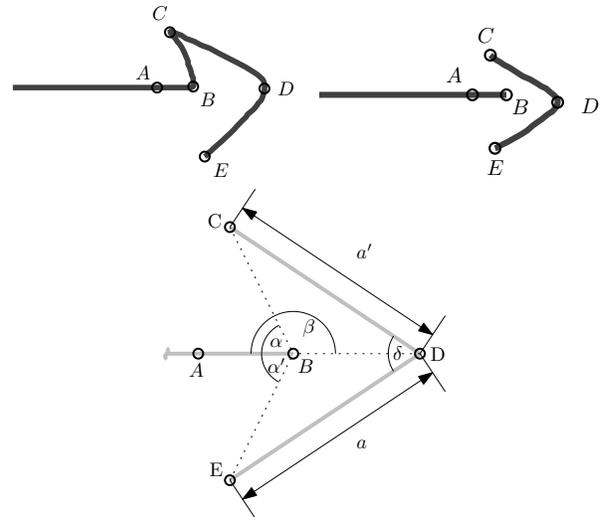


Figure 2. Above: The five characteristic points that define arrow shapes. Below: Numerical features used for arrow recognition

their bounding-box fits the square $[-0.5, 0.5] \times [-0.5, 0.5]$. The numerical features we extract after preprocessing are the coordinates of the five points, and the angles α , α' , β and δ , and the lengths a and a' as indicated in Fig. 2.

Given the stroke $(p_1, \dots, p_i, \dots, p_n)$, we developed a method to identify a characteristic points p_i as corner. It computes the angles α_k formed by p_i and its neighboring points p_{i-k} and p_{i+k} , for $k = 1, \dots, \ell$. If α_k exceeds a given threshold, then it is marked as corner angle. If the number of corner angles is greater than the non-corner angles, we mark p_i as corner. Some times, however, the same corner is located at a small number of consecutive points. We overcome this problem by substituting consecutive corner points with their center of mass, if they lie within a given small neighborhood.

Recognition of dashed shafts

Since some commutative diagrams also include arrows with dashed shafts, we developed a method to group a sequence of strokes into a shaft. Our method assumes that the user draws all segments in a dashed line at once. This assumption allow real-time grouping.

We use a classifier to decide whether a given stroke form part of a dashed line. If that is true, the current stroke is joined to the last one to extend the dashed line. In the other case, the dashed line is considered as "closed" and the current stroke is a candidate to generate a new dashed line.

The classifier considers the current stroke and the last n strokes in the dashed line. For each considered stroke, we compute the angles formed between middle, starting and

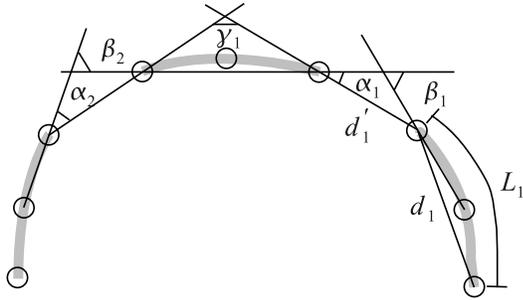


Figure 3. Features used to recognize dashed lines. Here we consider only two previous strokes.

end points as illustrated in Fig. 3. We also consider for every stroke in the n -sequence its length, the distance between its starting and end points, and the distance between its starting point and the end point of the previous stroke. Since not all dashed lines are formed with n strokes, we consider also another feature that indicates whether the previous n strokes exist. If the i -th stroke exists, $i = 1, \dots, n$, then the i -th is set to one and zero in the other case.

4. Recognition of diagram's layout

Computation of the initial grouping

This step generates the initial grouping using the *Minimum Spanning Tree (MST)* of a weighted graph. The nodes of the graph are the mathematical symbols and the points located at the middle, start and end of the arrow's shafts. The edge weight between a shaft point and a symbol is the Euclidean distance between the point and the center of the symbol's bounding-box. The weight of edges joining shaft points is defined as zero, even for points from different arrows. Using Prim's algorithm, the MST is build up starting with a shaft point. With our definition of the edge weight, the shaft points are added the MST at first and afterwards the algorithm adds the symbols to the tree.

After the MST construction, there are symbols that are a sibling of exactly one arrow point. Such symbols are used to initialize a grouping that is constructed recursively, by joining new symbols connected to symbols in the current grouping until an arrow is reached or no more symbols are found. Symbols that are siblings of middle points are used to initialize groupings that describe arrow's labels. Figure 4 shows the results of this step. Note that an actual expression in the upper right is split into two symbol groups. Since the groups created in this step are not split in further processing, we assume that a group does only contain symbols that belong to the same mathematical expression.

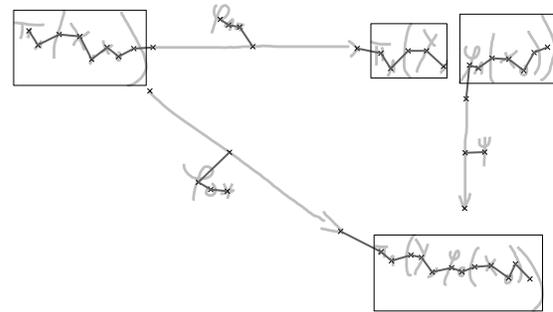


Figure 4. An example of an initial groping for a commutative diagram.

Diagram reconstruction

The second step uses the initial groupings together with our third assumption. It constructs a hypothesis that assigns to each grouping a row and a column of the tabular layout. Groupings assigned to the same row and column must be located in the same grid cell to form one mathematical expression. The initial hypothesis assigns each group the rows and columns in increasing order of the x and y -coordinates of the groupings' bounding boxes. We define the error function $e(h)$ to measure the quality of a given hypothesis h . Algorithm 1 generates new hypothesis that iteratively decrease the error function $e(h)$.

Algorithm 1: Algorithm to find the best derived hypothesis

Input: Hypothesis h
Output: Best derived Hypothesis

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result  $\leftarrow$   $h$ ;
error  $\leftarrow$   $e(h)$ ;
foreach adjacent column pair  $(i, j)$  of  $h$  do
  temp  $\leftarrow$   $h.merge(i, j)$ ;
  if  $e(temp) < error$  then
    result  $\leftarrow$  temp;
    error  $\leftarrow$   $e(temp)$ ;
  end
end
foreach adjacent row pair  $(u, v)$  of  $h$  do
  temp  $\leftarrow$   $h.merge(u, v)$ ;
  if  $e(temp) < error$  then
    result  $\leftarrow$  temp;
    error  $\leftarrow$   $e(temp)$ ;
  end
end
return result

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Once the algorithm converges, we found the best hypothesis. Groupings in the hypothesis that fall into the same

column and row form a single mathematical expression. Finally, we have only to assign the expressions to the arrows. The elements in the diagram that the arrows connect are the mathematical expressions nearest to some starting or ending point of arrows shafts. Expressions nearest to middle shaft points form the labels of the corresponding arrow. After we assign the expressions to the arrows, we apply our method [5] to convert into LaTeX the mathematical expressions, and then we create the xy-pic code of the diagram.

Error function

The error function $e(h)$ evaluates the quality of the current hypothesis (h). The error function is a linear combination of geometrical features $f(h)$ calculated for the hypothesis h :

$$e(h) = \sum_i \alpha_i \cdot f_i(h). \quad (1)$$

The next paragraphs describe each of the functions f_i used in our evaluation and based on column features. These functions depend of the following “global” values: the diagram’s width w_d and height h_d , and the average symbol width \overline{w}_s .

The first feature is the *Number of Columns* of the hypothesis. With an increasing number of columns, the probability to construct a wrong layout increases. Therefore, this feature forces the algorithm to use less columns.

$$f_1(h) = \frac{\overline{w}_s}{w_d} \cdot |h.\text{cols}| \quad (2)$$

The *Maximal Column Width* evaluates the width of the widest column. For an ideal diagram this feature will dramatically increase, when two groups of symbols from different columns are assigned to the same one.

$$f_2(h) = \frac{1}{\overline{w}_s} \cdot \max_{c \in h.\text{cols}} \text{width}(c) \quad (3)$$

The *Maximal Inner Column Distance* of a column d_i is computed from the distances between the projection of the symbols two the x -axis. This feature evaluates the position of the symbols in the columns. For larger gaps in the projections this feature will grow and therefore force the columns to have a compact arrangement of the symbols with respect to the projection.

$$f_3(h) = \frac{1}{\overline{w}_s} \cdot \max_{c \in h.\text{cols}} d_i(c) \quad (4)$$

The *Minimal Outer Column Distance* of a column d_o is the smallest distance of the column to the adjacent columns. It enforces a minimal distance between adjacent columns.

$$f_4(h) = \max(k_o - \frac{1}{\overline{w}_s} \cdot \min_{c \in h.\text{cols}} d_o(c), 0) \quad (5)$$

Table 1. Recognition rates for commutative diagrams.

	Accuracy
Objects	284 (97.59 %)
Rows	113 (94.96 %)
Columns	157 (97.52 %)
Diagrams	49 (92.45 %)

The *Use of Space* evaluates an approximation for the unused space of a column. The error for an hypothesis with columns that contain unused space will increase by this feature. The approximation ignores the possible overlapping of symbols. Usually overlapping of symbols is small and seldom.

$$f_5(h) = \frac{1}{w_d \cdot h_d} \cdot \max_{c \in h.\text{cells}} \left(\text{area}(c) - \sum_{s \in c.\text{symbols}} \text{area}(s) \right) \quad (6)$$

Please note that the error function also involves the features f_6, \dots, f_{10} associated with the rows. They are defined similarly to f_1, \dots, f_5 by replacing x with y , “column” with “row”, and “width” with “height”.

5. Experimental results

We used 53 commutative diagrams written from 3 different persons to evaluate our method. We choose the diagrams from publications and books about homological and topological algebra. The database contains in total 119 rows, 161 columns and 291 mathematical objects. We evaluated a mathematical object as correctly recognized, when all its symbols are grouped into the same expression. A column or row is correctly recognized when all its objects are recognized correctly. A diagram is correctly recognized, when all its columns and rows are recognized correctly. The coefficients α_i of the error (1) were determined manually. Table 1 shows the accuracy of the method for objects, rows, columns and diagrams.

We also used our 53 diagrams to evaluate our arrow recognizers. They contain 3785 strokes that form 1874 arrows. The classification of arrows reached a recognition rate of 98.24%. Since the database contains a reduced number of arrows with dashed shafts, we redraw the half of the diagrams using dashed arrows, generating in total 4911 strokes. In this case, we reached a recognition rate of 97.07%. We used in both cases a neuronal network from the Weka library [7]. The network for arrow classification has 18 input neurons, 10 hidden neurons and two output neurons. The network for the dashed shafts has 26 input neurons, 14 hidden neurons and two output neurons. We

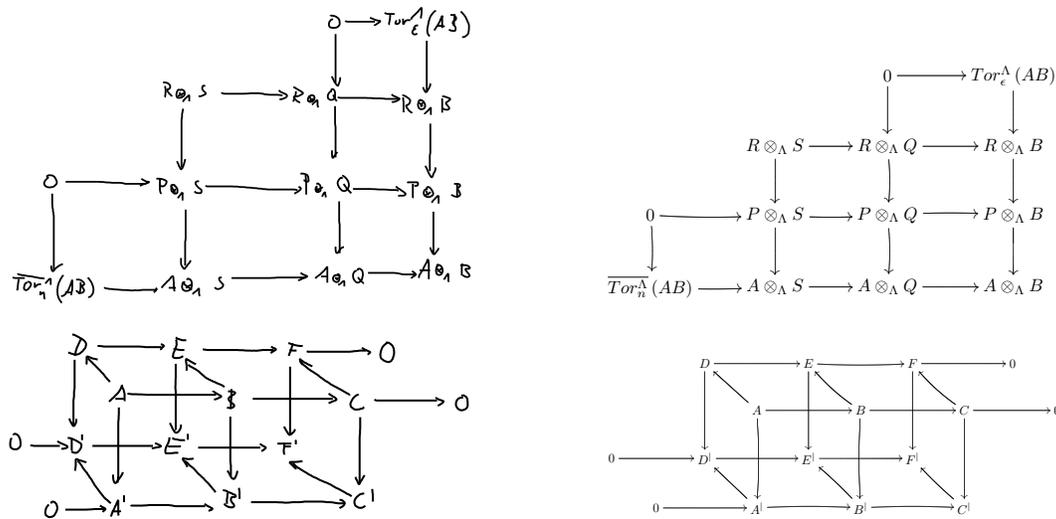


Figure 5. Two diagrams correctly recognized.

used the default values of Weka for learning rate, momentum and number of epochs.

6. Comments and further work

We presented a new method for the recognition of on-hand written mathematical diagrams. We used an optimization approach that considers local and global features of the groupings in the diagram. This approach is more robust and handles local writing irregularities. Figure 5 shows two examples of recognized diagrams. In our experiments, the start and end points of the arrows were always assigned to the correct expression. Therefore, the semantic of a diagram is not affected by a miss-assignment of the arrows to the expressions. As long as the symbols are assigned correctly to the expressions, the semantic of the diagram is not changed whether or not an expression is assigned to the wrong row or column. Problematic result the diagrams that do not satisfy the assumptions about the arrangement of the objects. Other causes of errors are the distances between columns or rows. When these distances are smaller than the distances between symbols within an object, the initial grouping of symbols leads to errors. In these cases the recognition of the corresponding rows and columns were also affected.

We also presented a method for the recognition of arrows and dashed lines. In both cases we had problems to discriminate mathematical symbols, because the current implementation works without symbol recognizers; it differentiates between arrows and non-arrows. We are sure that the recognition rates will improve, in particular the recognition of dashed lines, when using some symbol classifier or contextual information from the diagram. Our voting method used to locate corners in strokes is robust to small

irregularities. The classification rates for arrow recognition show indirectly that the voting method was well enough to recognize the characteristic points of arrows.

Since our method uses only the symbols' identity, size and position, our method could be easily extended to recognize off-line commutative diagrams. We consider that our method is general enough to recognize diagrams with a tabular layout similar to commutative diagrams.

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