

Jose C. Rubio

CONTACT INFORMATION	Advanced Driving Assistance Systems Group Computer Vision Center Universitat Autònoma de Barcelona Edifici O Campus UAB 080193 Bellaterra (Cerdanyola) Barcelona, Spain.	<i>E-mail:</i> jcrubio@cvc.uab.cat <i>Web:</i> www.cvc.uab.es/~jcrubio <i>Voice:</i> (34) 935-81-18-28 <i>Fax:</i> (34) 935-81-16-70
CITIZENSHIP	Spain	
RESEARCH INTERESTS	Bayesian Networks, Data Association, Video Sequence Understanding, Tracking, Graph Matching.	
EDUCATION	Universitat Autònoma de Barcelona , Barcelona, Spain PhD in Computer Vision, (thesis defense Sept. 2012) Oct. 2009 - present <ul style="list-style-type: none">• Advisor: Professor Joan Serrat• Area of Study: Graphical Models and Optimization M.S., Artificial Intelligence and Computer Vision, Sept. 2008 - Sept. 2009 <ul style="list-style-type: none">• Master Thesis: <i>Data association with graphical models for night vehicle detection</i> University of Portsmouth , Portsmouth, UK Erasmus student exchange program Sept. 2006 - June 2007 Final Year Project, <i>Kinematics of human motion</i> <ul style="list-style-type: none">• Developed an interactive kinematic simulation of human movement.• Investigated and applied concepts including direct and inverse kinematics, robotics, quaternion interpolation, and body dynamics.• Nominated for the best project award of the Computer Science department. Universitat de Valencia , Valencia, Spain Sept. 2000 - June 2007 M.S Computer Science	
RESEARCH EXPERIENCE	École Centrale Paris , Paris, France Sept. 2010 - March 2011 Six month internship at MAS Laboratoire, under the supervision of Professor Nikos Paragios. <ul style="list-style-type: none">• Proposed a hierarchical image representation to perform region matching using higher order graphs. Universitat Autònoma de Barcelona , Barcelona, Spain <ul style="list-style-type: none">• PhD Thesis: <i>Many-to-many high order feature matching, by means of inference on graphical models</i>• Proposed a multi-image unsupervised foreground segmentation method based on region matching.• Developed a hierarchical region-based image model to perform image understanding, segmentation and retrieval.• Proposed a multiple-target tracking and data association system to perform tracking in diverse scenarios.• Proposed a real-time system to track headlights in a real driving environment.	

TEACHING
EXPERIENCE

Universitat Autònoma de Barcelona, Barcelona, Spain

Teaching Assistant

Feb. 2009 - June 2012

- Software Engineering, UML Design and Patterns
- Conducted discussion sessions for students, and graded programming assignments, exams and projects.

PROFESSIONAL
EXPERIENCE

e-Movilia, Barcelona, Spain.

Software Developer (.NET framework)

August 2007 - May 2008

- Designed and implemented management utilities for PDAs in C#.

Software Developer (JAVA)

May 2008 - Sept. 2008

- Designed and implemented mobile tracking services managed through web and mobile interfaces.

PUBLICATIONS

Peer reviewed articles:

- **Jose C. Rubio**, Joan Serrat, Antonio Lopez, Nikos Paragios. Unsupervised co-segmentation through region matching. *IEEE International Conference on Computer Vision and Pattern Recognition 2012*
- **Jose C. Rubio**, Joan Serrat, Antonio Lopez. Multiple target tracking and identity linking under split, merge and occlusion of targets and observations. *International Conference On Pattern Recognition Applications and Methods 2012*.
- **Jose C. Rubio**, Joan Serrat, Antonio Lopez, Dani Ponsa. Multiple target tracking for intelligent headlight control . *IEEE Transactions in Intelligent Transportation Systems. (to appear)*
- **Jose C. Rubio**, Joan Serrat, Antonio Lopez, Dani Ponsa. Multiple Target Tracking for Intelligent Headlight Control. *Intelligent Transportation Systems Conference 2010*.
- **Jose C. Rubio**, Joan Serrat. Feature Matching with Graphical Models for Night Vehicle Detection. *Fourth CVC Workshop on the Progress of Research & Development 2009*

GRANTS

Awarded research grant for internship at École Centrale Paris by the Generalitat de Catalunya, 2010.

TECHNICAL SKILLS

Extensive programming experience in several languages and paradigms, including C/C++, Java and MATLAB. Proficient in object-oriented design and software patterns, as well as common software development tools and practices such as unit testing, design by contract, and version control.

Other programming skills: iOS, OpenGL, OpenCV, Ogre3D Engine.

LANGUAGES

Spanish: native language

Catalan: native language

English: proficient, TOEFL SCORE: 105/120